

# Control interface

[No product image available](#)

## Description

Control interface for the integration of the shaker in robotic systems (PLC)

- Relais output: shaker is running / stops
- Relais output: signal alarm / trouble-free operation
- Relais output: ready for operation
- Optocoupler input for external start/stop
- Analog input for setpoint of the speed
- Analog output for actual speed value

## Details

**Order No.::** 0052 932